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PUNE VIDYARTHI GRIHA'S

COLLEGE OF SCIENCE AND TECHNOLOGY

Affiliated to University of Mumbai

Question Bank

Class: S.Y.B. Sc.CS	Semester: IV
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Subject: Linear Algebra using Python

UNIT	1
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1.	The absolute value of 3+4i is
	A. 4
	B. 5
	C. 6
	D. 0
2.	In GF(2),1+1 is equal to
	A. 1
	B. 0
	C. 1 and 0
	D. 2
3.	i=
	A. 1
	B1
	C. square root of -1
	D. 0
4.	Galois field contain elements
	A. 0
	B. 1
	C. 2
_	D. 3
5.	The form of complex number is z=x+iy
	A. polar
	B. exponential
	C. cartesian
_	D. complex
6.	If $z=2+3i$ the $IzI=$
	A. 13
	B. square root of 13
	C. square root of 12
7	D. 12
7.	form of complex number is $z=r(\cos \theta + i\sin \theta)$

	A.	polar
	B.	exponential
	C.	cartesian
		complex
8.		led the of z
0.		
		amplitude
		arguement
		both amplitude and arguement
		modulus
9.	x is cal	led the part in z=x+iy
	A.	real
	B.	imaginary
	C.	partial
	D.	complex
10	v is cal	led the part in z=x+iy
	-	real
		imaginary
		partial
11		complex
11.		-(4+7i)=
		5i+11
		5+11i
		6+10i
		6i+10
12.		$\underline{\hspace{1cm}}$ is a set V over the field F with binary operation $+$ and .
		vector space
	B.	span
	C.	subspace
	D.	field
13.		is a subspace of V which is called as trivial subspace
	A.	
	B.	1
	C.	both 0 and 1
	D.	
14		uare root of 8-6i is
		3+i and 3-i
		3-i and -3+i
		-3+i and -3-i
1		3+i and -3-i
15.		is
		field
		vector space
		subspace
	D.	linear span
16.	If for x	, y belongs to V and $+$ is commutative in V then $x+y=$
	A.	x+y
	B.	y+x

C. y-x	
D. x-y	
17. Let V be a Vector Space and W be a non empty subset of V.bThen W is	of V iff
a.X+b.Y belongs to W where x,y belongs to W and a,b are real numbers	
A. field	
B. vector space	
C. subspace	
D. linear span	
18. If z=7+i then conjugate of z is	
A7-i	
B. 7-i	
C7+i	
D. 7+i	
19. If $z_1=2+i$ and $z_2=2-i$ then $z_1.z_2=$	
A. 4	
B. 5	
C. 6	
D. 8	
20. Conjugate of z=2+3i is	
A. 2-3i	
B2-3i	
C2+3i	
D. 2+3i	
21. There are forms of complex number z	
A. 1	
B. 2	
C. 3	
D. 4	
22. The absolute value of the number z = 1-i is:	
A. 2	
B. 0	
C. $\sqrt{2}$	
D. 4	£V
23. A non empty subset W of a vector space V over field F is called a of)1 V
A. Linear combination	
B. Basis	
C. Span	
D. Subspace	
24. The of two subspace is a subspace of V	
A. Union	
B. Intersection	
C. Linear combination	
D. Span	
25. The dot product of vectors $u=(1,-1,2)$ and $v=(2,-3,4)$ is	
A. 11	
B. 12	
C. 13	

	D.	18
26.	If u=(1	,2,3) and $v=(2,7,-5)$ then $ u =$
	A.	14
	B.	$\sqrt{14}$
	C.	6
	D.	36
27.	If $u=(1$	(2,3) and $v=(2,7,-5)$ then $ v =$
	A.	78
	B.	$\sqrt{78}$
	C.	14
	D.	4
28.	The set	of all linear combination of finite elements of S is called as of S
	A.	Linear span
	B.	Basis
	C.	Subspace
		Vector space
29.		s a complex number?
		A very small number that can't be expressed as a point on a two-dimensional plane.
		A number of the form $a + bi$, where a and b are real numbers, and $i = \sqrt{(-1)}$.
	C.	A number that involves real numbers a and b, where a/b is always an irrational
	_	number.
20		A number of the form ai + b, where the difference between ai and $b = \sqrt{(-1)}$
30.		o we find the complex conjugate of a complex number a + bi?
		We change the sign of bi.
		We change the sign of a.
		We don't do anything.
21		We change the sign of both a and bi. 2),1+1+1+1 is equal to
31.	III OI (2	A. 1
		B. 0
		C. 1 and 0
		D. 4
32	O is a si	ubspace of V which is called assubspace
32.		Trivial
		Zero
		Binary
		whole
33.		of the following is a complex number in standard form?
		3 - 4i
	B.	4i
	C.	12
	D.	-8i
34.	Find th	e product and simplify your answer. $(4 + 9i)(4 - 9i)$
	A.	97
	B.	-65
	C.	97 + 72i
	D.	-65 + 72i

35.	The ang	gle between two vectors is given as
	A.	$\ \mathbf{u}\ \ \mathbf{v}\ \cos\theta$
	B.	Uv
	C.	$u/vcos\theta$
	D.	u/v
36.	i ² =	_
	A.	1
	B.	-1
	C.	0
	D.	2
37.	r is call	ed as
	A.	amplitude
	B.	modulus
	C.	arguement
	D.	angle
38.	If $z_1 = -$	$-2 - 3i$ and $z_2 = 2 + 4i$, what is $z_1 + z_2$?
	A.	2+3 i
	B.	
	C.	i
	D.	0
39.		,5) and $v=(4,-2)$ then dot product is
	A.	
	B.	
	C.	
	D.	
40.		empty subset W of aV over field F is called a subspace of V
		vector space
		Linear combination
		Basis
		Span
41.		,9) and v=(7,11) then u+v is
		(11,20)
		(9,20)
		(2,20)
10		(5,20)
42.		_ field contains two elements
		Galois
		Vector
		Complex
12		Integer
43.		of all linear combination ofelements of S is called as linear span of S Infinite
		Finite
		Vector Scalar
11		id to be of v is ax+by∈W
44.		Vector space
		Subspace Subspace
	ъ.	Duospace

	C.	Linear combination
	D.	Linear span
45.	Norm o	of (2,-1,3) is
	A.	14
	B.	$\sqrt{14}$
	C.	28
	D.	15
46.	In GF(2	2),1.1+1.1 is equal to
	A.	
	B.	0
	C.	-1
	D.	2
47.	A vecto	or in which most of the component are zero is called vector
	A.	Zero
	B.	Unit
	C.	Sparse
	D.	Trivial
48.	$ \mathbf{u} =1$,	it is called as vector
	A.	Zero
	B.	Unit
	C.	Sparse
	D.	Trivial
49.	z=3+4i	, 3 is called the part
	A.	real
		imaginary
	C.	simple
		complex
50.	z=3+4i	, 4i is called the part
		A. real
		B. imaginary
		C. simple
		D. complex
		-
- 1	7 71 1	UNIT 2
51.		terminant of identity matrix is?
	A.	
	B.	
		Depends on the matrix
50	D.	
52.		minant of a matrix A is Zero than
		A is a Singular matrix
		A is a non-Singular matrix A is zero matrix
		A is zero matrix A is null matrix
52		
JJ.		verse exist only for matrices.
		Singular Noncingular
	D.	Nonsingular

D. Skew symmetric
54. A symmetric matrix is a one in which?
A. All diagonal elements are zero
B. All diagonal elements are 1
C. $A = A^T$
D. $A = -A^T$
55. A matrix having one row and many columns is known as?
A. Row matrix
B. Column matrix
C. Diagonal matrix
D. Scalar matrix
56. If A is a lower triangular matrix then A ^T is a
A. Upper triangular matrix
B. Lower triangular matrix
C. Diagonal matrix
D. Scalar matrix
57. There are methods to find inverse of matrix
A. 1
B. 2
C. 3
D. 4
58. For matrix A if $A.A^T = I$, where I is identity matrix then A is?
A. Orthogonal matrix
B. Nilpotent matrix
C. Idempotent matrix
D. Scalar matrix
59. A matrix having many rows and one column is known as?
A. Row matrix
B. Column matrix
C. Diagonal matrix
D. Scalar matrix
60. A square matrix $A = [aij]nxn$, if $aij = 0$ for $i > j$ then that matrix is known as
A. Upper triangular matrix
B. Lower triangular matrix
C. Unit matrix
D. Identity matrix
61. Any equation in n variables can be written in matrix form as AX=B
A. Linear
B. Homogeneous
C. Nonhomogeneous
D. trivial
62. Linear function is also known as
A. Linear map
B. Operator

C. Symmetric

•	C. Transformation
]	D. Subspace
63. Ker	=0 iff f is
	A. Injective
]	3. Surjective
(C. Bijective
	D. Isomorphic
	el of a linear function is
	A. Vectorspace
	3. Subspace
	C. Linear span
]	D. Map
65 Imag	e of a linear function is
_	A. Vectorspace
	3. Subspace
	C. Linear span
	D. Map
	of vectors are said to be linearly independent if all the scalars are
	A. 1
	3. 0
	C. Same
	D. Positive
	7. FOSILIVE
67. A se	of vectors are said to be if there exist atleast one nonzero scalar
67. A se	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent
67. A se	of vectors are said to be if there exist atleast one nonzero scalar
67. A se	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent
67. A se	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent C. linear combination
67. A se	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent C. linear combination D. linear span
67. A se	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent C. linear combination D. linear span stem of single nonzero vector is always
67. A se	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent C. linear combination D. linear span stem of single nonzero vector is always A. linearly independent
67. A see	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent C. linear combination D. linear span Stem of single nonzero vector is always A. linearly independent B. linearly dependent
67. A se	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent C. linear combination D. linear span Stem of single nonzero vector is always A. linearly independent B. linearly dependent C. linear combination
67. A se	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent C. linear combination D. linear span Stem of single nonzero vector is always A. linearly independent B. linearly dependent C. linear combination D. linear span
67. A se	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent C. linear combination D. linear span stem of single nonzero vector is always A. linearly independent B. linearly dependent C. linear combination D. linear span s of V is always
67. A se	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent C. linear combination D. linear span stem of single nonzero vector is always A. linearly independent B. linearly dependent C. linear combination D. linear span s of V is always A. linearly independent C. linearly independent C. linear span s of V is always A. linearly independent
67. A se	cof vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent C. linear combination D. linear span stem of single nonzero vector is always A. linearly independent B. linearly dependent C. linear combination D. linear span sof V is always A. linearly independent B. linearly independent B. linearly dependent B. linearly dependent B. linearly dependent C. linear combination D. linear span so of V is always A. linearly dependent C. linear combination D. linear span
67. A se	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent C. linear combination D. linear span Stem of single nonzero vector is always A. linearly independent B. linearly dependent C. linear combination D. linear span S of V is always A. linearly independent B. linearly independent C. linearly independent C. linearly independent C. linearly dependent
67. A se	a. linearly independent b. linear combination c. linearly independent c. linear span b. linearly independent c. linear span b. linearly independent c. linearly independent c. linearly independent c. linearly independent c. linear combination c. linear span c of V is always A. linearly independent c. linearly independent d. linearly independent c. linearly independent d. linearly independent c. linearly independent d. linearly dependent d. linearly dependent d. linear combination d. linear span d. combination of elements of B is equal to d. Vector space
67. A se	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent C. linear combination D. linear span Stem of single nonzero vector is always A. linearly independent B. linearly dependent C. linear combination D. linear span Stem of V is always A. linearly independent B. linearly dependent C. linear combination D. linear span Stem of V is always A. linearly dependent C. linear combination D. linear span B. linearly dependent C. linear combination D. linear span B. linearly dependent C. linear span B. linearly dependent C. linear span B. Subspace B. Subspace
67. A see	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linearly dependent C. linear combination D. linear span Stem of single nonzero vector is always A. linearly independent B. linear combination D. linear span Stem of V is always A. linearly independent B. linearly dependent B. linearly independent B. linearly dependent B. linearly dependent B. linearly dependent B. linearly dependent B. linear combination D. linear span B. C. linear combination D. linear span B. Subspace B. Subspace C. Linear span
67. A se	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linear combination C. linear span Stem of single nonzero vector is always A. linearly independent B. linearly dependent C. linear combination C. linear span S of V is always A. linearly independent B. linearly independent C. linear span S of V is always A. linearly dependent C. linear combination C. linear combination D. linear span A. Vector space B. Subspace C. Linear span D. Map
67. A see	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linear combination D. linear span stem of single nonzero vector is always A. linearly independent B. linearly dependent B. linear combination D. linear span B. of V is always A. linearly independent B. linearly independent B. linearly dependent B. linearly dependent B. linearly dependent B. linear combination D. linear span B. of V is always A. linearly independent B. linear span B. linear span B. linear span B. linear span B. Subspace B. Subspace B. Subspace B. Linear span D. Map B. of R ² consist of vectors
67. A see	of vectors are said to be if there exist atleast one nonzero scalar A. linearly independent B. linear combination C. linear span Stem of single nonzero vector is always A. linearly independent B. linearly dependent C. linear combination C. linear span S of V is always A. linearly independent B. linearly independent C. linear span S of V is always A. linearly dependent C. linear combination C. linear combination D. linear span A. Vector space B. Subspace C. Linear span D. Map

	C.	3
	D.	4
72.	Basis o	f R ³ consist of vectors
	A.	
	B.	2
	C.	3
	D.	4
73.		of vector space is defined as the number of vectors in the basis
	A.	Basis
	B.	Dimension
	C.	Linear span
	D.	Мар
7.4	N7 1	
/4.		r of non zero rows in the matrix determine the
		eigen value
		eigen vector rank
75		basis
15.		s equal to the number of rows in row echelon form
		linearly independent
		linearly dependent
		linear combination
7.		linear span
/6.		mension of row space is called the of matrix A
		Rank
		Nullity
		Kernel
77		Image
//.		nension of null space is called the of matrix A Rank
		Nullity Kernel
		Image
78		')+Nullity(T)=
70.		Basis of V
		Dim of V
		L(V)
		Subspace of V
79		is denoted by S^0
1).		Rank
		Nullity
		Annihilator
		Image
80		r equation with right side equal to zero is calledequation
55.		Linear system
		Saturated

	C.	Homogeneous
	D.	Non homogeneous
81.	A linea	r equation with right side not equal to zero is called
	A.	Linear system
	B.	Saturated
	C.	Homogeneous
	D.	Non homogeneous
82.	The nu	mber of elements in the basis set of a vector space V is called of the vector
	space	•
	_	Basis
	В.	Dimension
	C.	Image
		Kernel
83.	Any set	t containing vector is always linearly independent
		zero
		Unit
	C.	
		More than 2
84.		all of vectors is called linear span
		Linear system
		linear combination
		linear operator
		linear map
85		trix A, $(A^T)^T$ is equals to
05.	A.	
		A^{T}
		Zero
	D.	
86	Σ.	umber od rows is equal to the number of column then it is called as matrix
00.		Scalar
		Square
		Diagonal
		Identity
87		conditions are important for basis
07.	—— `A.	
	А. В.	
	Б. С.	
00	D.	
88.		f vectors are said to be linearly dependent if there exist one nonzero scalar
		Atleast
		Atmost
		Maximum
00		Minimum
89.		f a identity matrix of order 2x2 is
	Α.	
	В.	2

	C.	3
	D.	4
90.	Rank o	f a identity matrix of order 3x3 is
	A.	
	В.	2
	C.	
	D.	
91.	A	is a sequence of vertices and edges
		Walk
		Path
		Trial
		Cycle
	Σ.	Syelle
92.		is a walk in which no vertex is repeated
		Path
		Cycle
		Circuit
		Trial
93.		is a in which the starting and ending points are same
		Cycle
		Path
		Trial
		Circuit
94.	The sol	ution set of the linear system is called null space of A
	A.	Homogeneous
		Nonhomogeneous
	C.	Similar
	D.	Dissimilar
95.	If A is	a upper triangular matrix then A ^T is a
		Upper triangular matrix
	В.	Lower triangular matrix
	C.	Diagonal matrix
	D.	Scalar matrix
96.	A path	is a walk in which no is repeated
	A.	Vertex
	B.	Edge
	C.	Points
	D.	lines
97.	The sol	ution set of the homogeneous linear system is called space of A
	A.	Null
	B.	Rank
	C.	echelon
	D.	kernel
98.		form of complex no is $z = r.ei\theta$
	A.	cartesian
	B.	polar

	C. exponential
	D. complex
99. Th	ne additive identity in vector space addition is
	A. 1
	B. 0
	C1
	Dv
100.	θ is called the of z
	A. argument
	B. modulus
	C. rank
	D. null space
	UNIT 3
101.	$ A - \lambda I = 0$ is called equation
	A. Quadratic
	B. Linear
	C. Characteristic
	D. NULL
102.	A vector space together with inner product is called space
	A. Vector
	B. Inner product
	C. Null
	D. Subspace
103.	Two vectors are orthogonal to each other if their inner product space is
	A. 1
	B. 0
	C1
	D. V
104.	n is called
	A. eigen value
	B. eigen vector
	C. constant
	D. variable
105.	The product of all eigen values of the matrix is equal to the of the matrix
	A. Determinant
	B. Rank
	C. Null space
	D. image
106.	A rectangular array of m rows & n columns is called
	A. Matrix
	B. Rank
	C. Image
	D. Kernel

107.		is a method for solving a system of linear equations
	A.	Row echelon
	В.	Gauss elimination
	C.	Adjoint method
	D.	Rank
108.		The of a vector v is denoted by v
	A.	Norm
	В.	Image
	C.	Rank
	D.	kernel
109.		If $u=(2,3,-1)$ and $v=(6,-3,-2)$ then $d(u,v)=$
	A.	$\sqrt{48}$
	В	$\sqrt{53}$
		48
		53
110.	۵.	If $u=(1,0,2,-4)$ and $v=(0,3,4,2)$ then $ u+v ^2=$
110.	A.	
		10
		50
		40
111.		If u and v are orthogonal to w then is orthogonal to w
	Α.	U+v
		U-v
		Uv
		u/v
112.		Two vectors are parallel to each other if <u, v="">=</u,>
	A.	
	В.	0
	C.	-1
		uv
113.		Two vectors are perpendicular to each other if <u, v="">=</u,>
	A.	
	В.	0
		-1
		uv
114.		If a vector v is orthogonal to every vector $w \in W$ then
	A.	V.w=0
	В.	V+w=0
	C.	V-w=0
	D.	v/w=0
115.		An of A is a vector which satisfies Av= \(\eta_{\text{V}}\)v
	A.	Eigen value
	В.	Eigen vector
	C.	Rank
	D.	nullity
		$\begin{bmatrix} 3 & -1 & 1 \end{bmatrix}$
116.		If $A = \begin{bmatrix} 3 & -1 & 1 \\ -1 & 3 & -1 \\ 1 & -1 & 3 \end{bmatrix}$ then eigen values are

		7)=1,1,5
		$\mathfrak{I}=2,2,5$
		$\mathfrak{I}=1,2,5$
	D.	$\mathfrak{I}_{}=1,5,5$
117		If $A = \begin{bmatrix} 1 & -3 \\ -4 & 5 \end{bmatrix}$ then eigen values are
		$\mathfrak{I}=1,7$
		n =-1,7
		n =-1,-7
	D.	$\mathfrak{I}_{=1,-7}$
118		If $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ then eigen values are
		<u> 7)=-1,5</u>
		$\mathfrak{I}=2,5$
		7)=-1,2
		$\mathfrak{I}_{=5,3}$
119).	If $A = \begin{bmatrix} 1 & 1 & 3 \\ 1 & 5 & 1 \\ 3 & 1 & 1 \end{bmatrix}$ then eigen values are
	A.	$\mathfrak{I} = -2,3,6$
		$\mathfrak{I}_{=1,2,3}$
		$\eta = 1, 3, 4$
		$\eta = -1, 3, 5$
120).	If A is a, then its eigen values are the diagonal elements
	A.	Upper triangular matrix
	B.	Lower triangular matrix
	C.	Scalar matrix
	D.	Diagonal matrix
121	•	A matrix A of order n is diagonalizable, iff it has n eigen vectors
	A.	linearly independent
	B.	linearly dependent
	C.	linear combination
	D.	linear span
122	. .	A square matrix B of order n is said to be to A if B=P ⁻¹ AP
	A.	Similar
	В.	Dissimilar
	C.	Inverse
	D.	Rank
123	i.	If B is similar to A then it has same
	A.	Eigen values
	B.	Rank
	C.	Nullity
	D.	Kernel
124		Solve the following equation by Gauss elimination method
	x+z=-1	1; $y+z=-4$; $4x+y+z=0$ then the values of x,y,z are
A.	1,2,3	
B.	1,-2,-2	

C.	1,-1,-1	
D.	1,1,1	
125	5.	Solve the following equation by Gauss elimination method
	x+y+ z	=2; 2x-3y+2z=-1; x+y-3z=6 then the values of x,y,z are
	A.	1,2,3
		1,2,-1
		1,1,1
		1,2,-4
126		The eigenvalues of a 4×4 matrix [A] are given as 2,-3,13, and 7. The det(A) is
120		546
		19
		25
	D.	
	D.	50
127	,	What is Eigen value?
14/		A vector obtained from the coordinates
		A matrix determined from the algebraic equations
		A scalar associated with a given linear transformation
100		It is the inverse of the transform
128		Two vectors are to each other if <u, v="">=1</u,>
		Parallel
		Perpendicular
		Similar
		Dissimilar
129		Two vectors are to each other if <u, v="">=0</u,>
		Parallel
		Perpendicular
	C.	Similar
	D.	Dissimilar
130).	The goal of Gauss elimination method is to reduce the coefficient matrix to a
		matrix
		Diagonal
	В.	Identity
	C.	lower triangular
	D.	upper triangular
131	•	In Gaussian elimination method, original equations are transformed by using
	A.	Column operations
	B.	Row Operations
	C.	Mathematical Operations
	D.	Subset Operation
132	2.	The Elimination process in Gauss Elimination method is also known as
	A.	Forward Elimination
	B.	Backward Elimination
	C.	Sideways Elimination
	D.	Crossways Elimination

133.		How the transformation of coefficient matrix A in Gauss Elimination method to
up	per t	riangular matrix is done?
	A.	Elementary row transformations
	B.	Elementary column transformations
	C.	Successive multiplication
	D.	Successive division
134.		Find the values of x, y, z in the following system of equations by gauss Elimination
M	ethoo	
		2, 4, 6
		2, 7, 6
		3, 4, 6
	D.	2, 4, 5
135.		Theof all eigen values of the matrix is equal to the determinant of the
m	atrix	
	A.	Sum
	В.	Product
	C.	Difference
	D.	division
136.		The angle between vector $u=(1,2,1)$ and $v=(3,1,2)$ is
		$Cos^{-1}(7/184)$
		$Cos^{-1}(1/184)$
		$\cos^{-1}(5/184)$
=	D.	$\cos^{-1}(3/184)$
137.		The angle between vector $u=(1,1,0)$ and $v=(0,0,1)$ is
	A.	2
	B.	$\frac{\pi}{\epsilon}$
	C.	$\frac{\pi}{2}$
	D.	1
138.		$ A - \lambda I X = 0$ will give
	Eig	gen value
	Ch	aracteristic equation
		gen vector
	Ra	nk
139.		If $u=(1,2,3,4)$ and $v=(2,3,4,5)$ and $w=(4,5,6,7)$ then $< u,v > is$
	A.	28
		38
		58
		48
140.		If $u=(1,2,3,4)$ and $v=(2,3,4,5)$ and $w=(4,5,6,7)$ then $\langle v,w \rangle$ is
	A.	25

133.

	В.	55
	C.	68
	D	37
141.	υ.	If a matrix is in echelon form, the non zero rows form the of row space
141.		_
		Basis
	В.	Rank
	C.	Image
	D.	Nullity
142.		x 0
	٨	. <u>></u>
	B.	
	C.	
	D.	=
143.		The projection vector of $u=(1,-1,1)$ along $v=(1,2,0)$ is
	Δ	$(\frac{-1}{2},\frac{2}{5},0)$
		(1,0,1)
	C.	(1,1,0)
	D.	(0,1,1)
144.		The projection vector of $u=(2,-1,1)$ along $v=(1,2,0)$ is
	A.	
	В.	
	C.	
	D.	
145.		If $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ then $ A = \underline{\hspace{1cm}}$
		-0 1-
	A.	
		-2
	C.	4
	D.	6
146.		The equation for is $ u+v ^2 = u ^2 + v ^2$
	A.	Inner product space
		Basis
		Pythagoras theorem
		Gauss elimination
1.47	υ.	
147.		The angles between the vectors is given by
		$\cos \theta$
	В.	$\sin \theta$
	C.	$\operatorname{Tan} \theta$
	D.	$\cot \theta$
148.		$ x =0 \text{ if } x_{\underline{}}0$
1.01	A.	
	В.	
	C.	=
	D.	<i>≠</i>
149.		A matrix B of order n is said to be similar to A if B=P ⁻¹ AP
	A.	Square
		Scalar
	٠.	

- C. Diagonal
- D. Unit
- D. Offit

 If u=(1,2,3) then unit vector is_____

 A. $(\frac{1}{\sqrt{14}}, \frac{2}{\sqrt{14}}, \frac{3}{\sqrt{14}})$ B. (1,2,3)C. $(\frac{1}{14}, \frac{2}{14}, \frac{3}{14})$ D. (1,4,9)150.